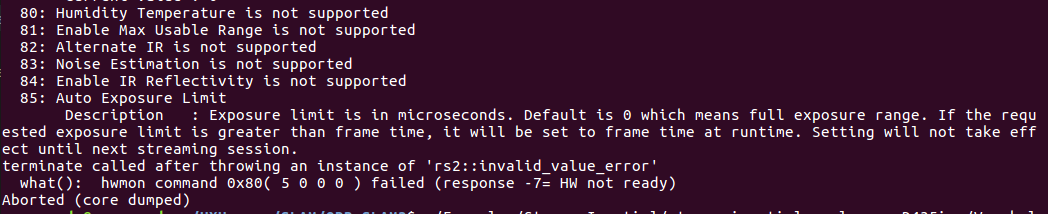
RGBD-Inertial执行指令

./Examples/RGB-D-Inertial/rgbd\_inertial\_realsense\_D435i ./Vocabulary/ORBvoc.txt ./Examples/RGB-D-Inertial/RealSense\_D435i.yaml

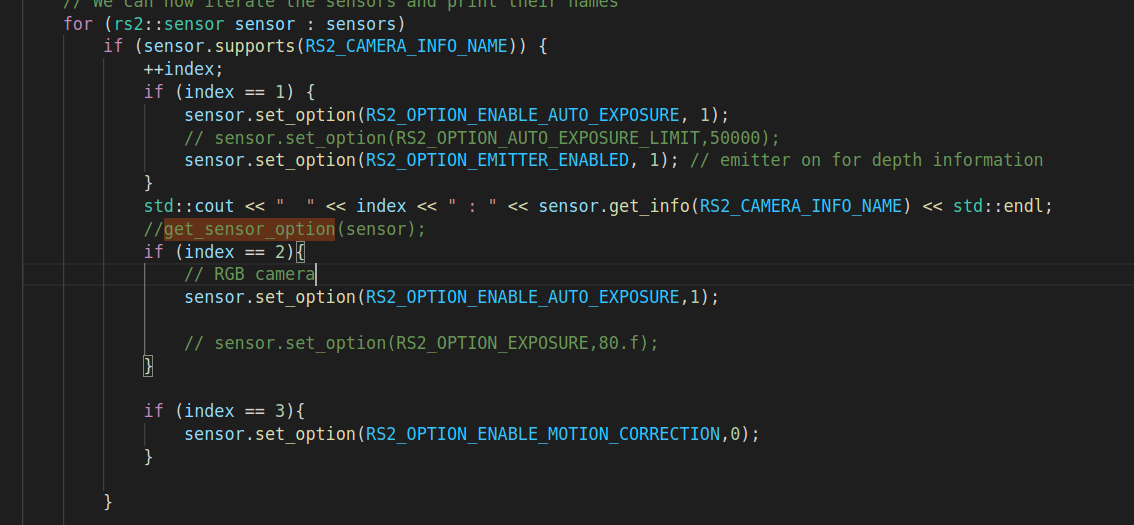
出现错误



解决办法

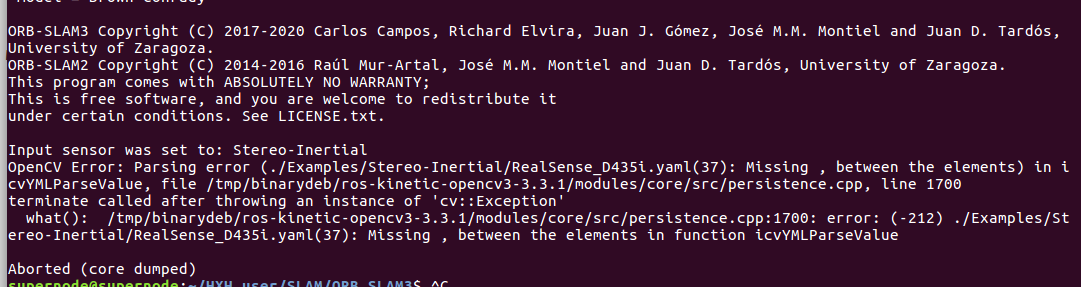
屏蔽代码文件rgbd\_inertial\_realsense\_D435i.cc

函数get\_sensor\_option(sensor);



Stereo-Inertial执行指令

./Examples/Stereo-Inertial/stereo\_inertial\_realsense\_D435i ./Vocabulary/ORBvoc.txt ./Examples/Stereo-Inertial/RealSense\_D435i.yaml



解决办法

原因：目录里的参数文件RealSense\_D435i.yaml 用的还是RGBD的.yaml文件，

将 ./Examples/Stereo-Inertial/RealSense\_D435i.yaml

替换为 ./Examples\_old/Stereo-Inertial/RealSense\_D435i.yaml

再根据打印标定参数修改yaml文件